

## 1 Investment with adjustment costs and taxation<sup>2</sup>

Firm owns productive capital  $K_t$  that generates output  $F(K_t)$  ( $F_K > 0, F_{KK} \leq 0$ ) and evolves according to  $K_{t+1} = (1 - \delta)K_t + I_t$ . Output can be transformed into investment goods  $I_t$  one for one, but investment entails convex adjustment costs of  $\Psi(I_t, K_t)$ :  $\Psi_I > 0, \Psi_{II} > 0, \Psi_K < 0, \Psi_{KK} > 0$  and  $\Psi_I(\delta K, K) = 0$ , i.e. marginal adjustment cost is zero when investment just replaces depreciating capital. One commonly used functional form is  $\Psi(I, K) = \frac{p s i_0}{2K} (I - \delta K)^2$ .

Corporate profits are subject to taxation characterized by the following rules:

- Operating profit is taxed at rate  $\tau$ .
- Depreciation allowance. Capital expenditures can be deducted from taxable profit at depreciation schedule  $D_s$ , where  $s = 0, 1, 2, \dots$  is the number of periods since the capital was installed. Assume that  $D_s$  follows a simple linear rule: every period a constant fraction  $\delta$  of the *initial* value of capital can be deducted, i.e. for tax purposes capital fully depreciates after  $1/\delta$  periods.
- Investment tax credit: A fraction  $\kappa$  of capital expenditures can be subtracted from the tax bill immediately.
- Assume that the above rules symmetrically apply if before-tax profit is negative, in which case firm gets a refund.

Firm starts with initial level of capital  $K_0$  and is choosing optimal investment policy to maximize present value of after-tax profits, discounted at interest rate  $r$ ,  $V(K_0)$ .

1. Formulate firm's decision problem. Pay attention to all the tax rules.

$$V(K_0) = \max_{\{I_t, K_{t+1}\}} \sum_{t=0}^{\infty} \frac{1}{(1+r)^t} \left[ (1-\tau)(F(K_t) - \Psi(I_t, K_t)) - (1-\kappa)I_t + \tau \sum_{s=0}^{\infty} D_s I_{t-s} \right]$$

s.t.  $K_{t+1} = (1-\delta)K_t + I_t$

2. Denote the shadow value of capital by  $q_t$ . Write down the Lagrangian and characterize firm's optimal investment policy.

We can rearrange summation as

$$\sum_{t=0}^{\infty} \frac{1}{(1+r)^t} \tau \sum_{s=0}^{\infty} D_s I_{t-s} = \sum_{t=0}^{\infty} z I_t + A_0,$$

where  $z = \tau \sum_{s=0}^{\infty} \frac{D_s}{(1+r)^s}$  and  $A_0 = \tau \sum_{t=0}^{\infty} \frac{1}{(1+r)^t} \tau \sum_{s=0}^{\infty} D_{-1-s} I_{-1-s}$ . Note that  $A_0$  is predetermined when decision is made at  $t = 0$ .

<sup>1</sup>By Anton Babkin. This version: April 17, 2016.

<sup>2</sup>Adapted from Hayashi (1982) "Tobin's marginal q and average q: a neoclassical interpretation", *Econometrica*.

Rewrite the problem as

$$V(K_0) = \max_{\{I_t, K_{t+1}\}} \sum_{t=0}^{\infty} \frac{1}{(1+r)^t} [(1-\tau)(F(K_t) - \Psi(I_t, K_t)) - (1-\kappa-z)I_t] + A_0$$

$$\text{s.t. } K_{t+1} = (1-\delta)K_t + I_t$$

Lagrangian:

$$L = \sum_{t=0}^{\infty} \frac{1}{(1+r)^t} [(1-\tau)(F(K_t) - \Psi(I_t, K_t)) - (1-\kappa-z)I_t + q_t((1-\delta)K_t + I_t - K_{t+1})] + A_0$$

Taking first order conditions

$$[I_t] : q_t - (1-\kappa-z) = (1-\tau)\Psi_I(I_t, K_t)$$

$$[K_{t+1}] : (1+r)q_t = (1-\tau)(F_K(K_{t+1}) - \Psi_K(I_{t+1}, K_{t+1})) + q_{t+1}(1-\delta)$$

FOC in  $[I_t]$  can be used to solve for optimal  $I_t$  as a function of current  $K_t$  and  $q_t$ .

3. Assume that firm starts at the steady state. Use phase diagram to describe firm behavior after an unanticipated policy change that allows to depreciate capital for tax purposes at a faster rate  $\hat{\delta} > \delta$  (depreciation rule is still linear, and physical depreciation is not affected).

We will be building phase diagram in  $(K_t, q_t)$  space.

Rewrite FOCs as

$$K_{t+1} - K_t = \Psi_I^{-1}\left(\frac{q_t - (1-\kappa-z)}{1-\tau}, K_t\right) - \delta K_t$$

$$q_{t+1} - q_t = \delta q_{t+1} + r q_t - (1-\tau)(F_K(K_{t+1}) - \Psi_K(I_{t+1}, K_{t+1}))$$

The expression for the  $\Delta K = 0$  isocline is simply a horizontal line  $q_t = 1-\kappa-z$  because by assumption  $\Psi_I(\delta K, K) = 0$ .  $\Psi_I$  is increasing in first argument since  $\Psi_{II} > 0$ , so  $\Psi_I^{-1}$  is increasing too. Then if  $q_t$  is above  $\Delta K = 0$  line  $K_{t+1} - K_t > 0$ , and below the line  $K_{t+1} - K_t < 0$ .

The expression for the  $\Delta q = 0$  isocline is  $q_t = \frac{1}{\delta+r}(1-\tau)(F_K(K_{t+1}) - \Psi_K(I_{t+1}, K_{t+1}))$ . It is a downward sloping line because by assumptions  $F_{KK} \leq 0$  and  $\Psi_{KK} > 0$ . When  $q_t$  and  $K_t$  are big  $q_{t+1} - q_t > 0$ , and below the line  $q_{t+1} - q_t < 0$ .

Remember expression for present value of depreciation allowances:  $z = \tau \sum_{s=0}^{\infty} \frac{D_s}{(1+r)^s}$ . If  $D_s$  for smaller capital age  $s$  becomes larger,  $z$  increases.

Dynamics of the system after the shock is shown in Figure 1.  $q_t$  immediately jumps down to the new saddle path, and system gradually converges to the new steady state with higher level of capital.

4. (Hayashi theorem). Show that if  $F(K)$  and  $\Psi(I, K)$  are linearly homogenous, then Tobin's marginal  $q$  and average  $Q \equiv V/K$  are related as  $q = Q + \hat{A}$ , where  $\hat{A}$  is a constant.

Rewrite the FOC in  $[K_{t+1}]$  multiplied by  $K_{t+1}$ :

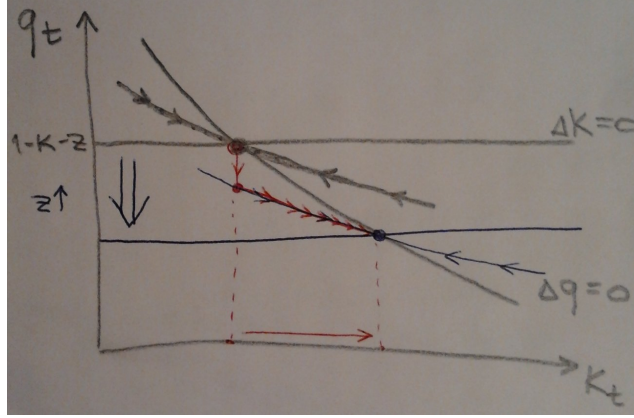


Figure 1: Phase diagram of the increase in  $z$ .

$$(1+r)q_t K_{t+1} = (1-\tau)(F_K(t+1)K_{t+1} - \Psi_K(t+1)K_{t+1}) + q_{t+1}K_{t+1}(1-\delta)$$

By Euler theorem  $F(K) = F_K K$  and  $\Psi(I, K) = \Psi_I I + \Psi_K K$ . Use this to manipulate the above equation:

$$\begin{aligned} (1+r)q_t K_{t+1} &= (1-\tau)(F(t+1) - (\Psi(t+1) - \Psi_I(t+1)I_{t+1})) + q_{t+1}K_{t+1}(1-\delta) \\ (1+r)q_t K_{t+1} &= (1-\tau)(F(t+1) - \Psi(t+1)) + (1-\tau)\Psi_I(t+1)I_{t+1} + q_{t+1}K_{t+1}(1-\delta) \end{aligned}$$

Substitute  $(1-\tau)\Psi_I(t+1)$  from the FOC in  $[I_t]$ :

$$\begin{aligned} (1+r)q_t K_{t+1} &= (1-\tau)(F(t+1) - \Psi(t+1)) + (q_{t+1} - (1-\kappa-z))I_{t+1} + q_{t+1}K_{t+1}(1-\delta) \\ (1+r)q_t K_{t+1} &= (1-\tau)(F(t+1) - \Psi(t+1)) - (1-\kappa-z)I_{t+1} + q_{t+1}(I_{t+1} + K_{t+1}(1-\delta)) \\ (1+r)q_t K_{t+1} &= (1-\tau)(F(t+1) - \Psi(t+1)) - (1-\kappa-z)I_{t+1} + q_{t+1}K_{t+1} \\ q_t K_{t+1} &= \frac{1}{1+r} [(1-\tau)(F(t+1) - \Psi(t+1)) - (1-\kappa-z)I_{t+1} + q_{t+1}K_{t+1}] \end{aligned}$$

Substitute  $q_t K_{t+1}$  forward recursively:

$$\begin{aligned} q_0 K_1 &= \sum_{t=1}^{\infty} \frac{1}{(1+r)^t} [(1-\tau)(F(K_t) - \Psi(I_t, K_t)) - (1-\kappa-z)I_t] + A_1 + \lim_{T \rightarrow \infty} \frac{1}{(1+r)^T} q_T K_{T+1} \\ &= \frac{1}{(1+r)} V(K_1) - A_1 \end{aligned}$$

$$\text{So } q_0 = \frac{1}{(1+r)} V(K_1)/K_1 - A_1/K_1 = \frac{1}{(1+r)} Q_1 - A_1/K_1.$$

*This is as close as I could get to the original result by Hayashi which was proved in continuous time.*

5. Describe a way to test the model with a simple OLS regression if you observed  $K_t, I_t$  and market value of firms. What would happen if you didn't include taxation rules into the model, or if assumptions of part 4 did not hold?

Let the adjustment cost function take the form  $\Psi(I, K) = \frac{\psi_0}{2K}(I - \delta K)^2$ . The the FOC in  $[I_t]$  becomes

$$(1 - \tau)\psi_0\left(\frac{I_t}{K_t} - \delta\right) = q_t - (1 - \kappa - z)$$

Rearrange to get a regression equation:

$$\frac{I_t}{K_t} = \delta + \frac{1}{\psi_0}\tilde{q}_t,$$

where  $\tilde{q}_t = \frac{q_t - (1 - \kappa - z)}{(1 - \tau)}$ . Applying Hayashi theorem,  $q_t$  is estimated as  $q_t = Q_t + A_t/K_t$ , where  $Q_t \equiv \frac{V_t}{K_t}$  is the Tobin's average q.

If one simply used an OLS regression to estimate

$$\frac{I_t}{K_t} = \delta + \frac{1}{\psi_0}Q_t,$$

estimates would be biased as  $Q_t \neq q_t$ .